

Roulette Inflation [hep-th/0612197](#)

J. Richard Bond Lev Kofman Sergey Prokushkin
Pascal M. Vaudrevange



24.08.2007

Outline

Introduction

Determining the potential

Trajectories

Stochastic regime

Conclusions

Calculating the potential

$$V = e^K \left(K^{i\bar{j}} D_i W D_{\bar{j}} \bar{W} - 3|W|^2 \right) \quad , \quad D_i = \partial_i + K_i, \quad K_i = \frac{\partial K}{\partial T^i}, \quad K_{i\bar{j}} = \frac{\partial^2 K}{\partial T^i \partial \bar{T}^{\bar{j}}}$$

$$V(T_1, \dots, T_n) =$$

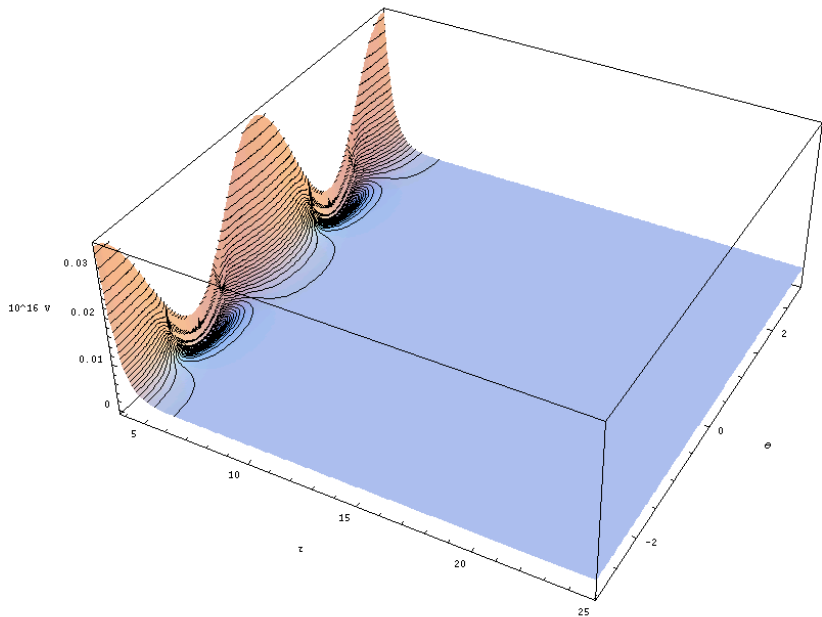
$$\begin{aligned} & \frac{12W_0^2\xi}{(4\mathcal{V}-\xi)(2\mathcal{V}+\xi)^2} + \sum_{i=2}^n \frac{12e^{-2a_i\tau_i}\xi A_i^2}{(4\mathcal{V}-\xi)(2\mathcal{V}+\xi)^2} + \frac{16(a_i A_i)^2 \sqrt{\tau_i} e^{-2a_i\tau_i}}{3\alpha\lambda_2(2\mathcal{V}+\xi)} \\ & + \frac{32e^{-2a_i\tau_i} a_i A_i^2 \tau_i (1 + a_i \tau_i)}{(4\mathcal{V}-\xi)(2\mathcal{V}+\xi)} + \frac{8W_0 A_i e^{-a_i\tau_i} \cos(a_i \theta_i)}{(4\mathcal{V}-\xi)(2\mathcal{V}+\xi)} \left(\frac{3\xi}{(2\mathcal{V}+\xi)} + 4a_i \tau_i \right) \\ & + \sum_{\substack{i,j=2 \\ i < j}}^n \frac{A_i A_j \cos(a_i \theta_i - a_j \theta_j)}{(4\mathcal{V}-\xi)(2\mathcal{V}+\xi)^2} e^{-(a_i \tau_i + a_j \tau_j)} [32(2\mathcal{V}+\xi)(a_i \tau_i + a_j \tau_j \\ & + 2a_i a_j \tau_i \tau_j) + 24\xi] \end{aligned}$$

Stabilization and Uplift

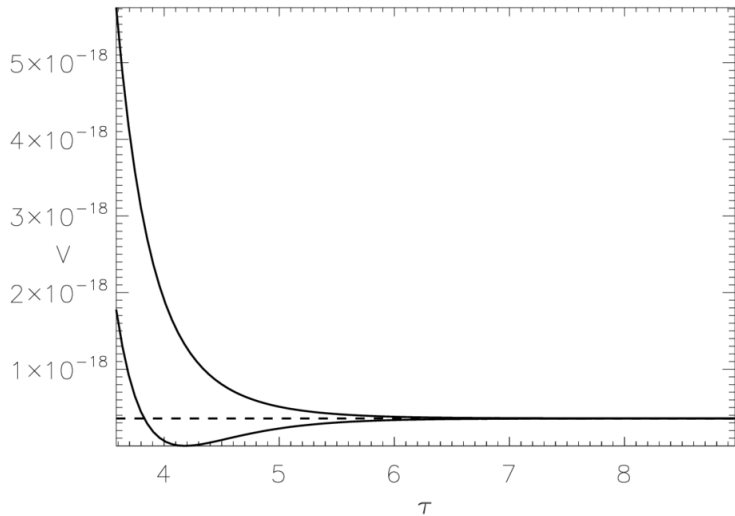
- ▶ At least 3 complex fields $(T_1, T_2, T_3) \Leftrightarrow (\mathcal{V}, T_2, T_3)$
- ▶ inflaton T_2
- ▶ Stabilization through extra fields $T_3 \dots T_n$: $\sum_{i=2}^n \frac{\lambda_i}{a_i^{3/2}} \gg \frac{\lambda_2}{a_2^{3/2}}$
- ▶ self-consistent uplift procedure
- ▶ inflaton $T_2 \equiv \tau + i\theta$

$$V(\tau, \theta) = \frac{8(a_2 A_2)^2 \sqrt{\tau} e^{-2a_2 \tau}}{3\alpha \lambda_2 \mathcal{V}_m} - \frac{4W_0 a_2 A_2 \tau e^{-a_2 \tau} \cos(a_2 \theta)}{\mathcal{V}_m^2} + \Delta V$$

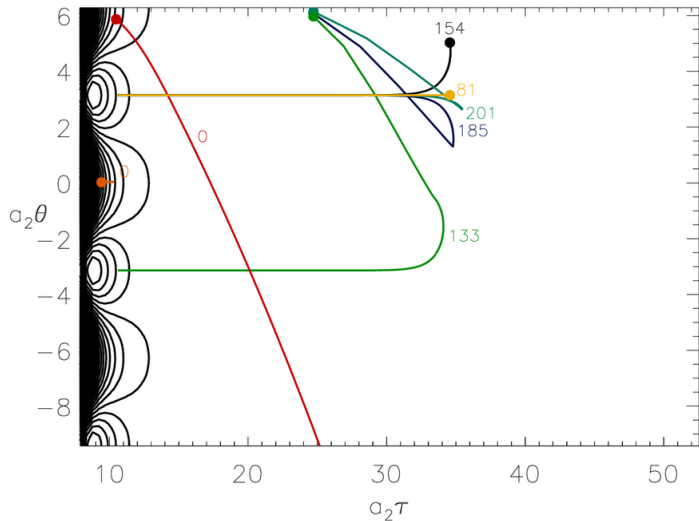
The Roulette Wheel...



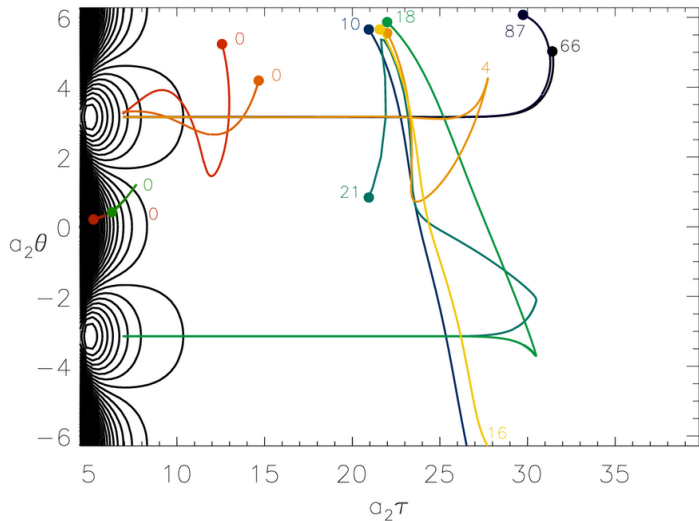
... is only a little rigged



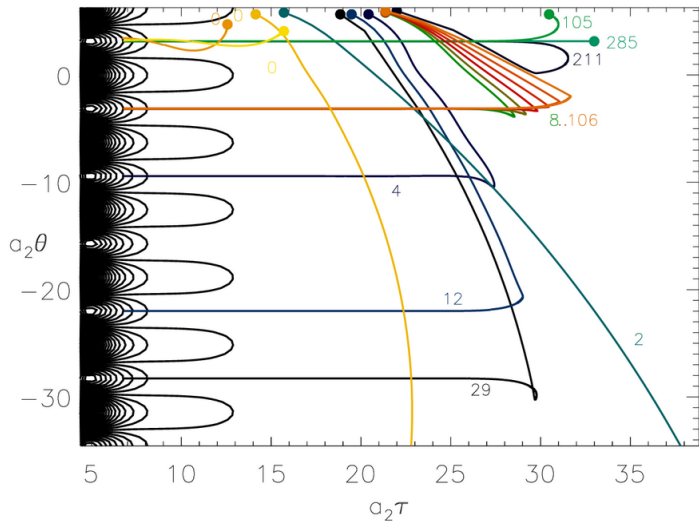
Viable trajectories



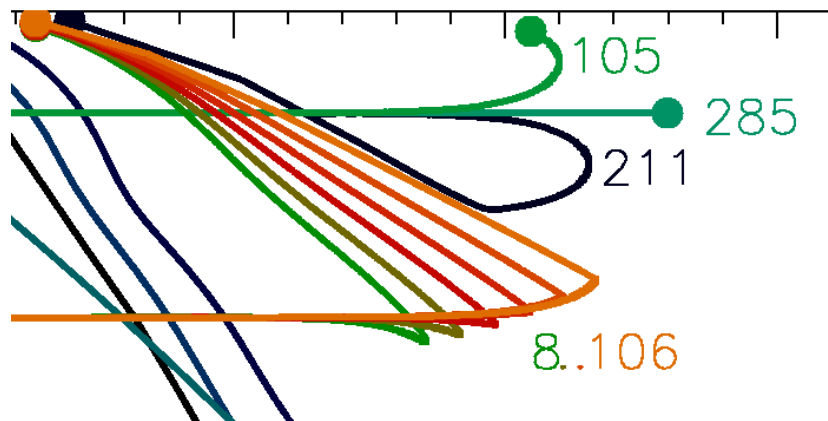
Viable trajectories



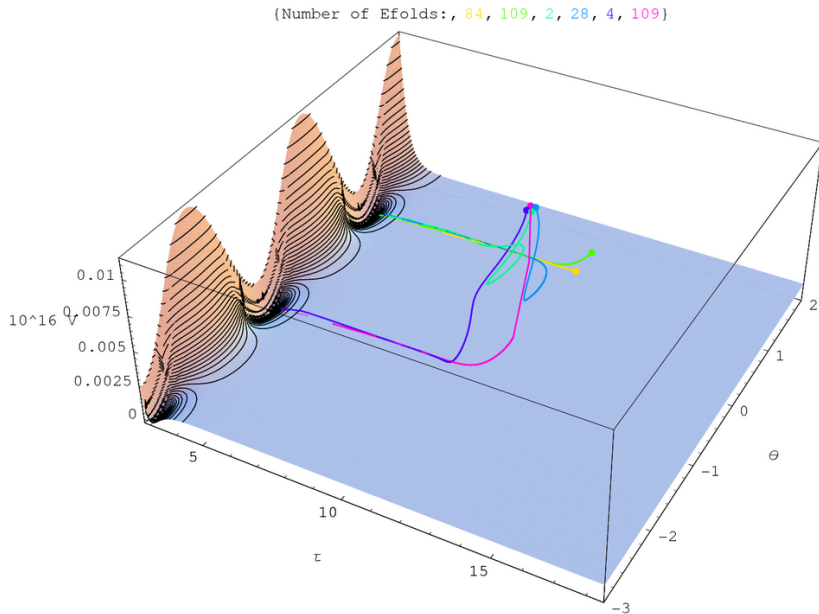
Viable trajectories



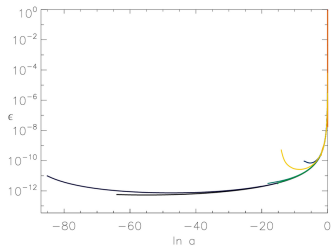
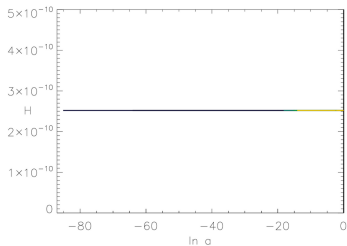
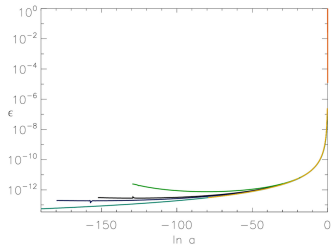
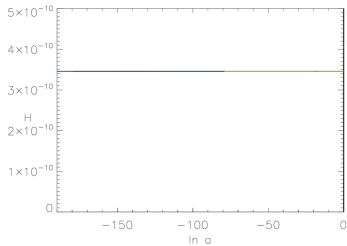
Importance of Initial conditions



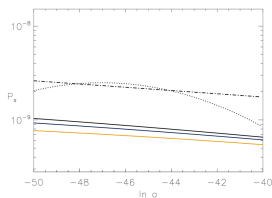
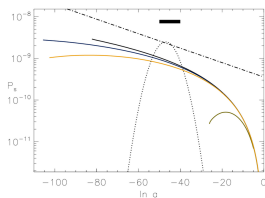
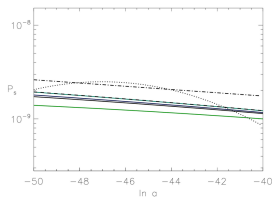
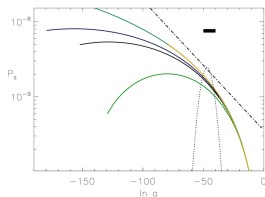
Trajectories on the wheel



Hubble and ϵ



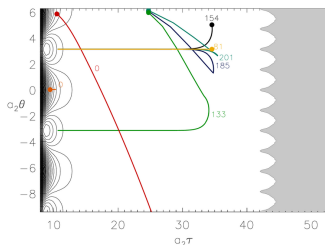
Scalar and tensor power spectra



Template $P_S \propto k^{n_s-1}$ with a) dash-dot: $n_s = 0.95$, $n_{\text{run}} = 0$
 b) dotted: $n_s = 0.95$, $n_{\text{run}} = -0.055$, pivot point $N = 45$

Initial conditions

- ▶ Stabilization from 3rd ... n^{th} field $T_3 \dots T_n$
- ▶ $\Rightarrow$ uniform (?) distribution of initial values of (τ, θ)
- ▶ maybe existence of region of eternal inflation? $\Rightarrow$ YES!



Conclusions

- ▶ Trajectories determined by
 - ▶ Parameters
 - ▶ Initial conditions
- ▶ Axionic direction
- ▶ Bifurcation points
- ▶ Lots of e folds
- ▶ Stochastic regime